PreciseFlex[™] c10 4-Axis Robot -

Energy Efficiency while Maximizing Workspace

1 1 1

1 . 1

```
most reliable, most energy-efficient

Wide Range of Applications

10
(1/1), 11
Lowest Power Consumption

Highest Workspace Density

11
Highest Workspace Density

12
Highest Reliability

13
Highest Reliability

14
Highest Reliability

15
Range of Motion
```

(|| [1] (| | (| _)](|| (|) (_)

PreciseFlex c10 - Specifications- preliminary

Payload	10
Max Cartesian Speed	/ , 00 / . , 00 /
Max Joint Speed	
J1 J2 J3 J4	00 / 00 / 0 / 0 /
Max Acceleration	000 / 1 1
Repeatability	_0.0 0 I fI
Range of Motion	
Joint 1 (Base)	٦
Joint 2 (Z-axis)	00,1000,1 0
Joint 3 (Elbow)	+1 +1
Joint 4	_ 0
Horizontal Reach	
Communications	
General	100_ , /
Operator Interface	- 1 1 1
Digital I/O	1 , !! ! , . 100 !
Facilities	
Power	0 . A ,! , 0- 0, 0-1 ! ! !
Pneumatics	

